

HIGH-FREQUENCY TESTING FOR FATIGUE BEHAVIOUR AND XCTE SPIN-OFF

D-STANDART Final Dissemination Event
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What We Do

Timeline

The XCTE Approach

The Test Method

Data Analysis &
Exploitation

The Impact

Closing

Get
Started



SPIN-OFF: XCTE

Journey & Next Steps

WHAT WE DO

Accelerated, vibration-based **performance testing** for composites, tracking dynamic properties in real time **to reveal** degradation and **fatigue behaviour** orders **faster** than classic campaigns.

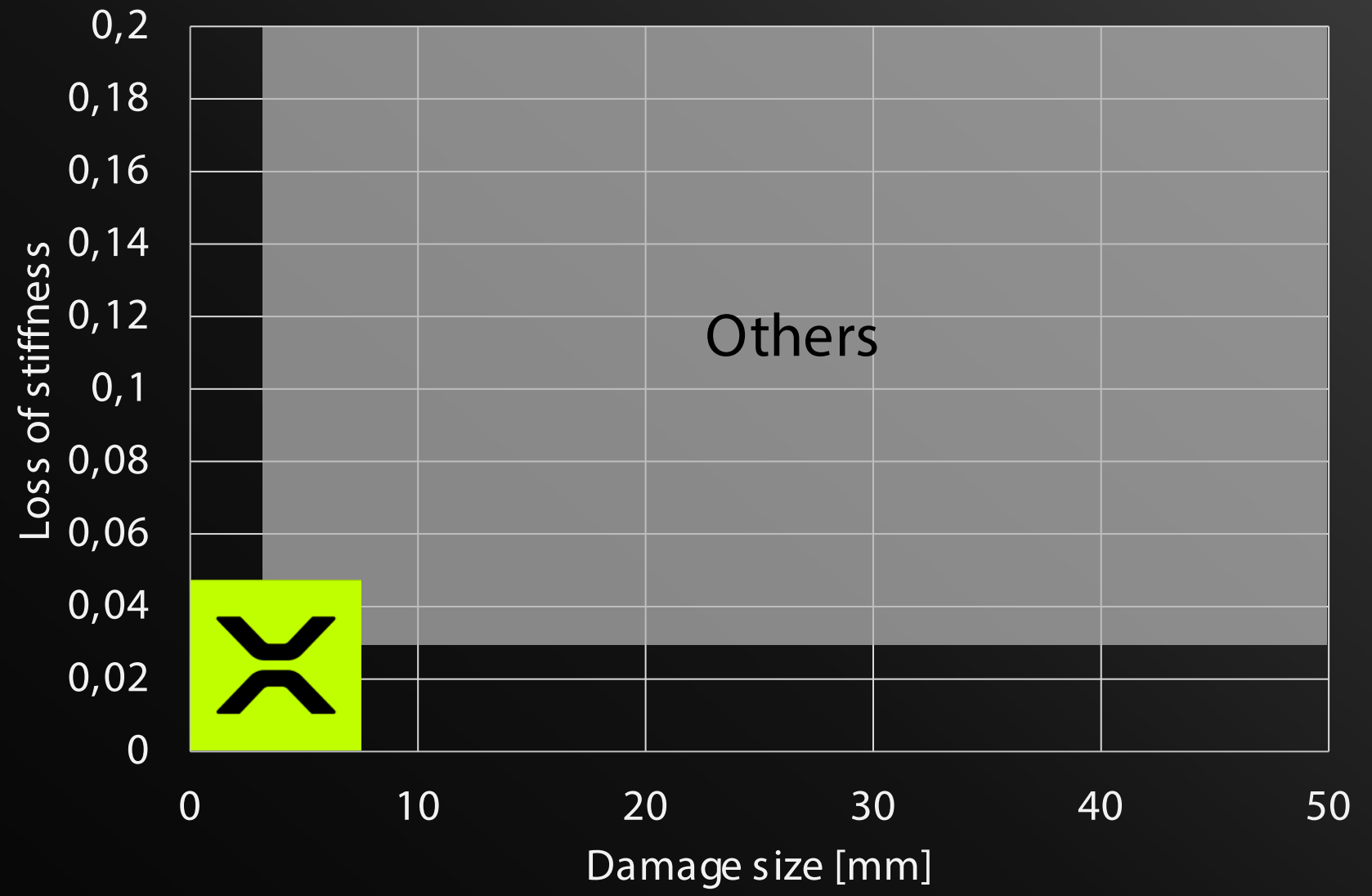
WHAT WE DO

- Front-end layer to test workflows:
 - Screen, rank and characterise early
 - Run standard tests more efficient
- Data driven design choices

THE XCTE APPROACH

- High frequency excitation of specimens
- Continuous tracking of dynamic properties
- Software analytics detect onset and progression of degradation
- Output: Relative performance ranking

THE XCTE APPROACH



TIMELINE



FUTURE VISION

- **Correlation & Validation:** Mapping to standard fatigue outcomes
- **Create Business Model:** Testing-as-a-service + later product
- **Commercialisation:** Hardware + control + analytics
- **Data & Models:** Growing a materials-behaviour dataset
- **Standards alignment:** Pre-standardisation work; documented protocols

HIGH-FREQUENCY TESTING FOR FATIGUE BEHAVIOUR

The testing method explained

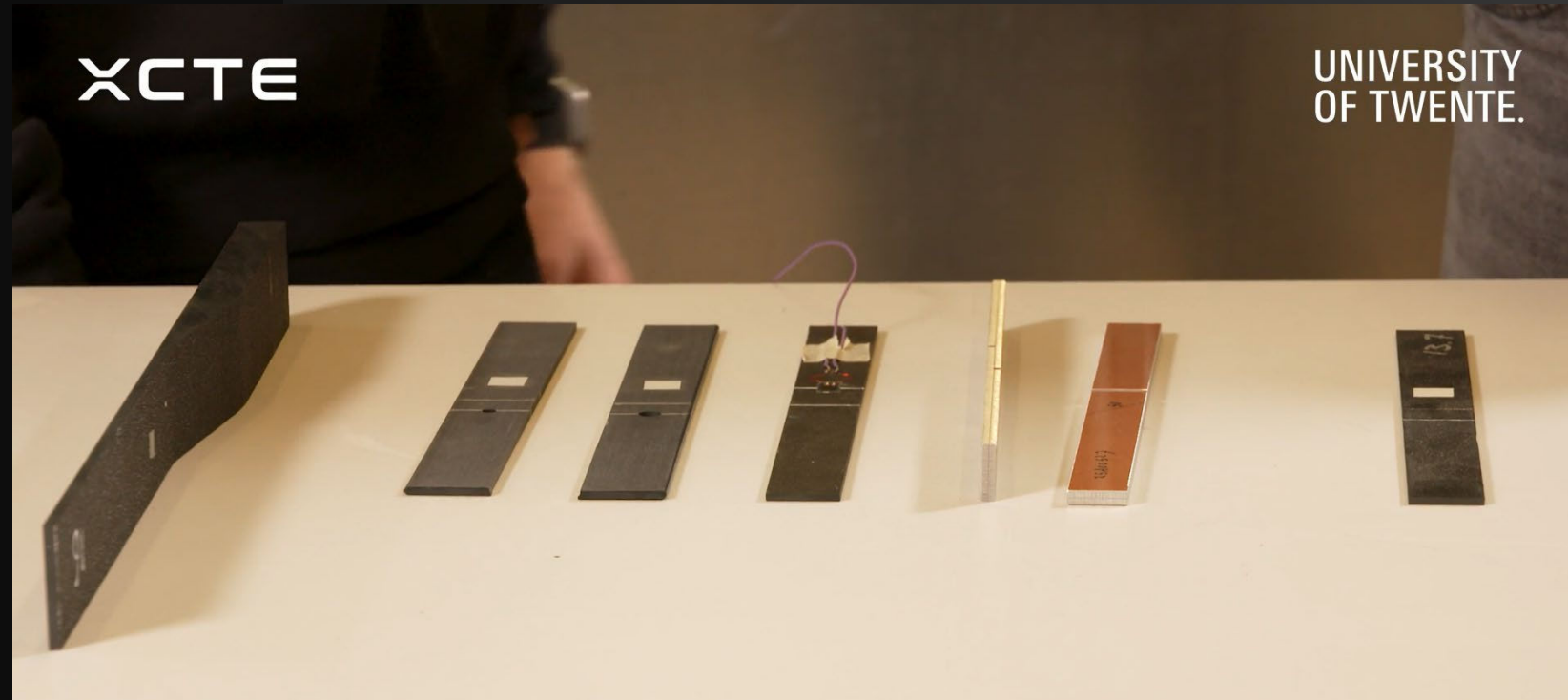
SAMPLE SELECTION

- Cut ply
- Milled coupon
- Drilled hole



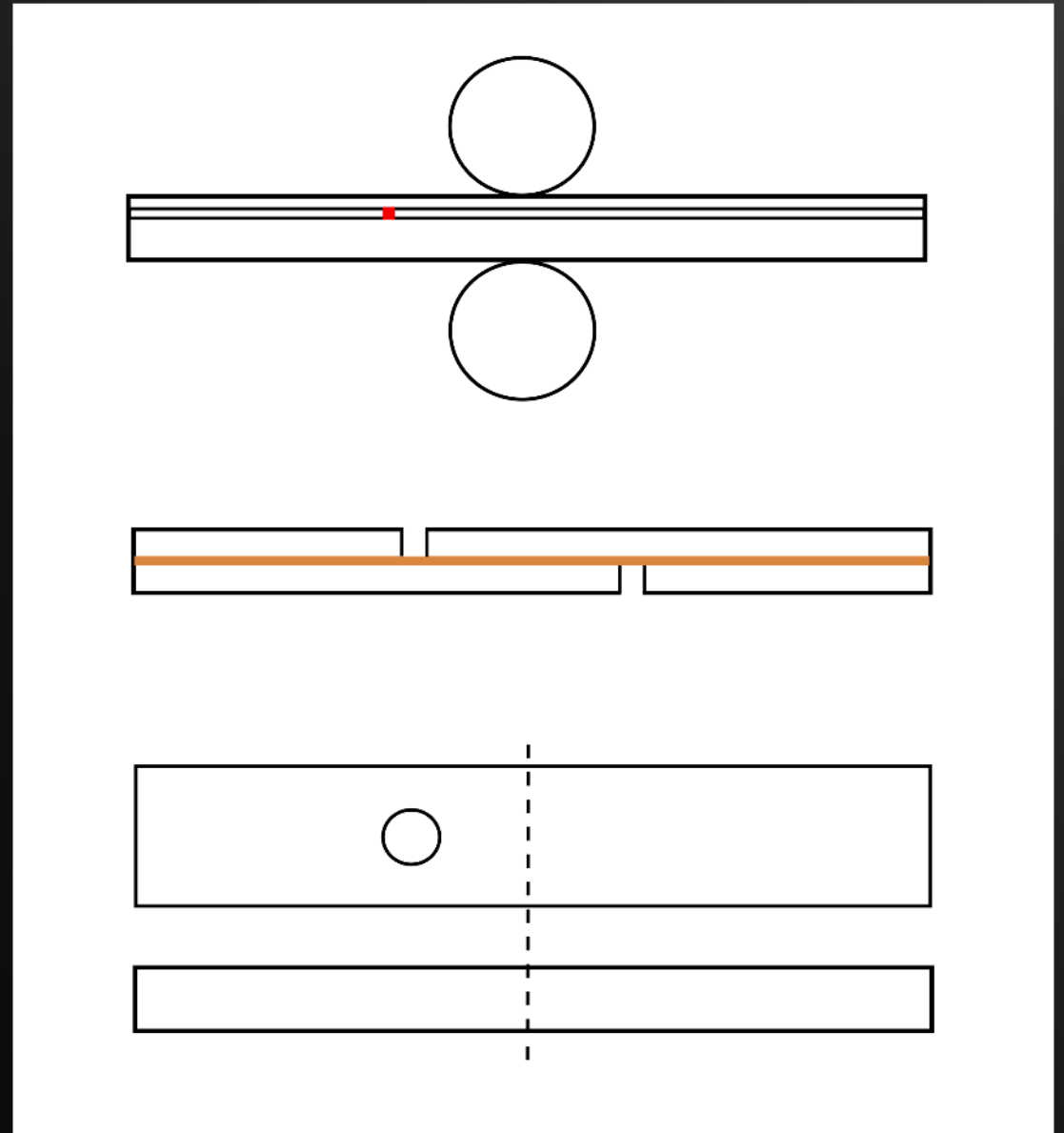
SAMPLE SELECTION

- Cut ply:
 - Laminate properties
 - Feature properties
- Milled coupon:
 - Adhesives testing
- Drilled hole:
 - Test existing materials



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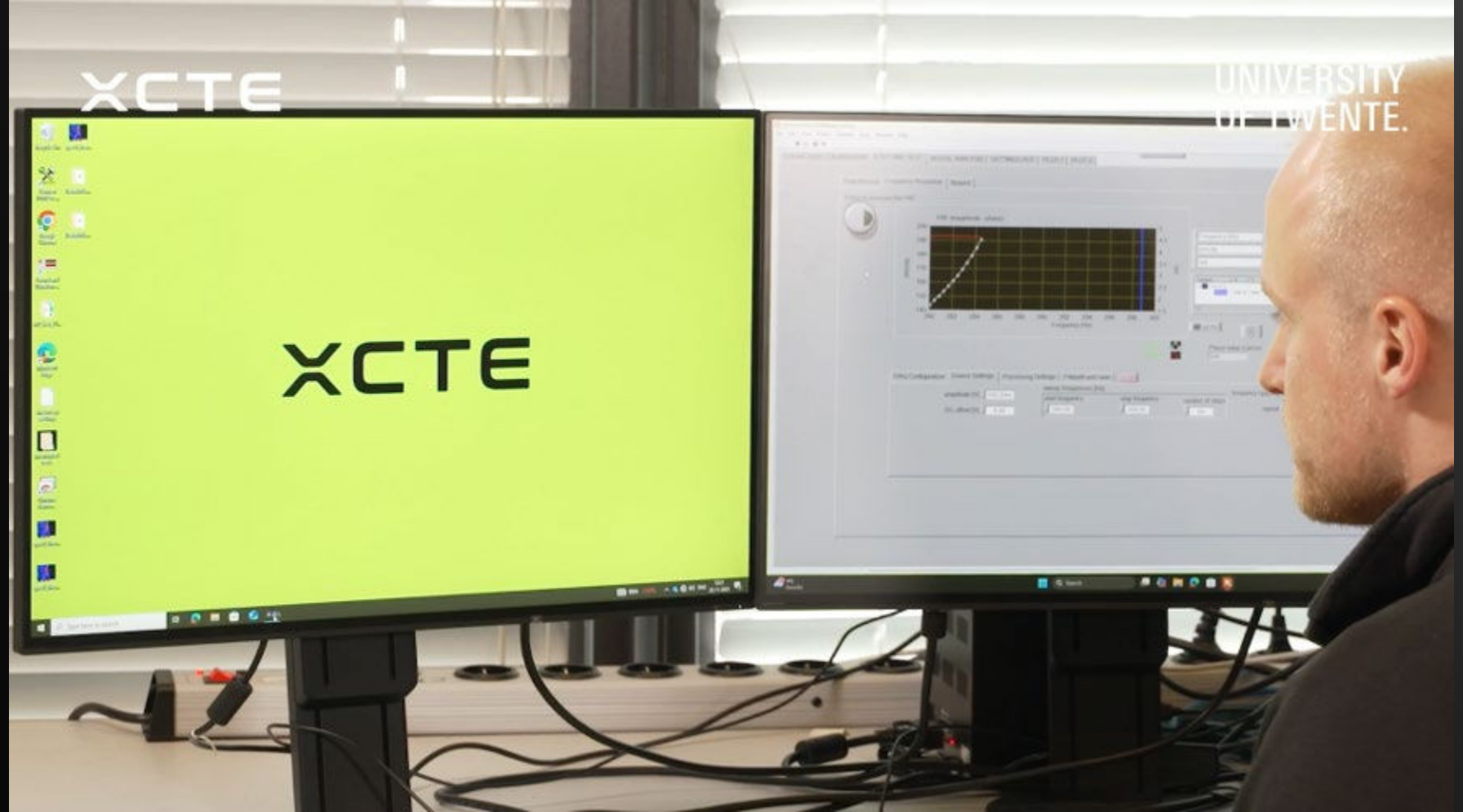


SETTING UP

- Alignment
- Applying torque

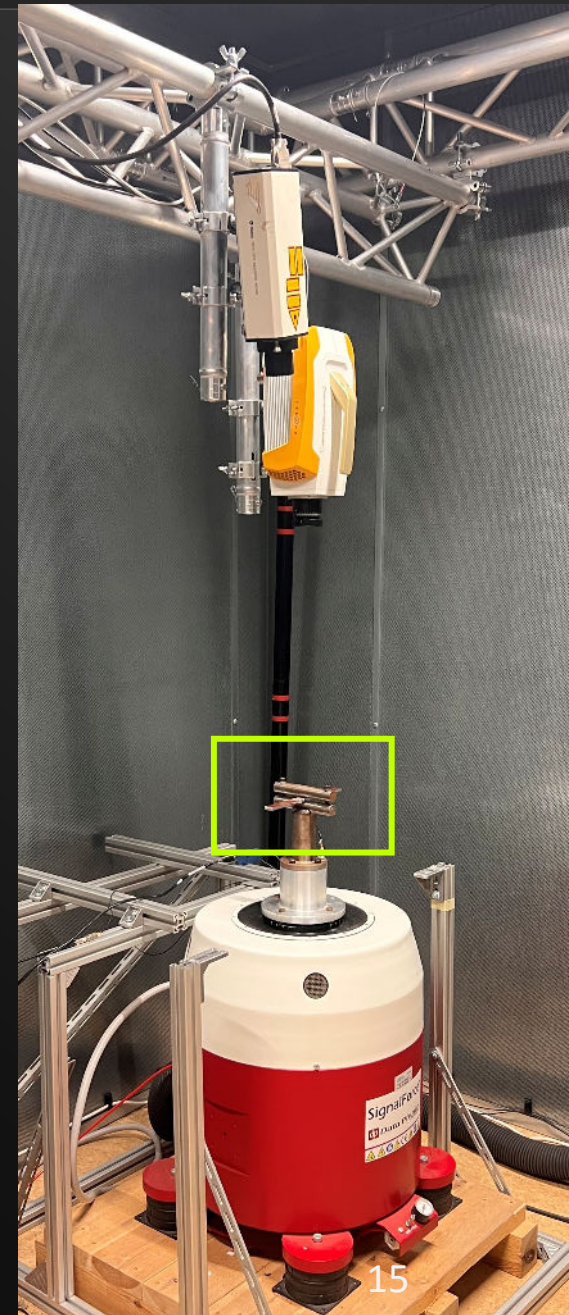
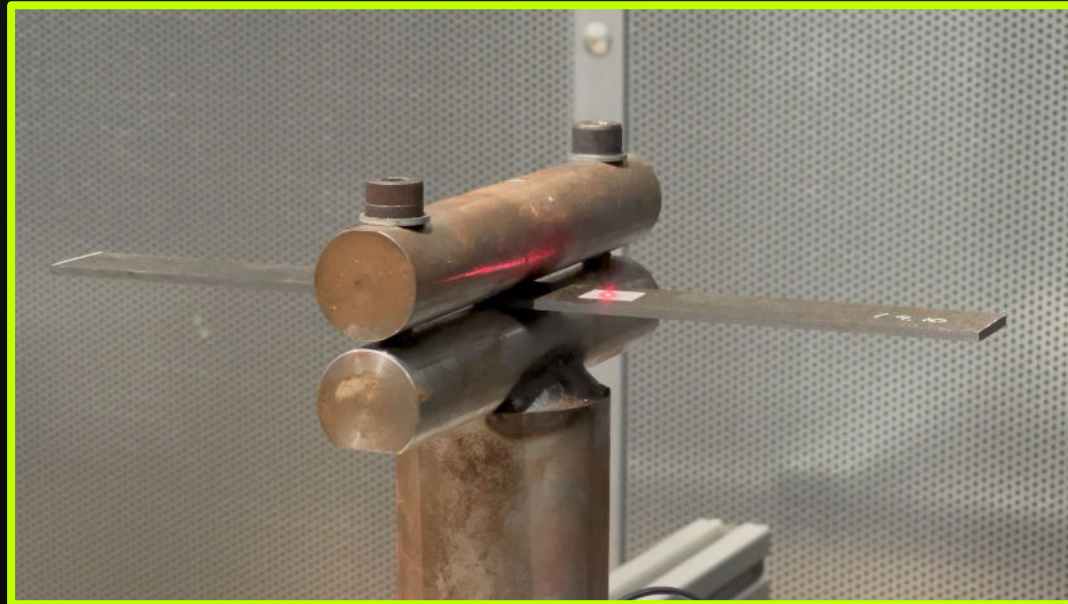


THE SETUP

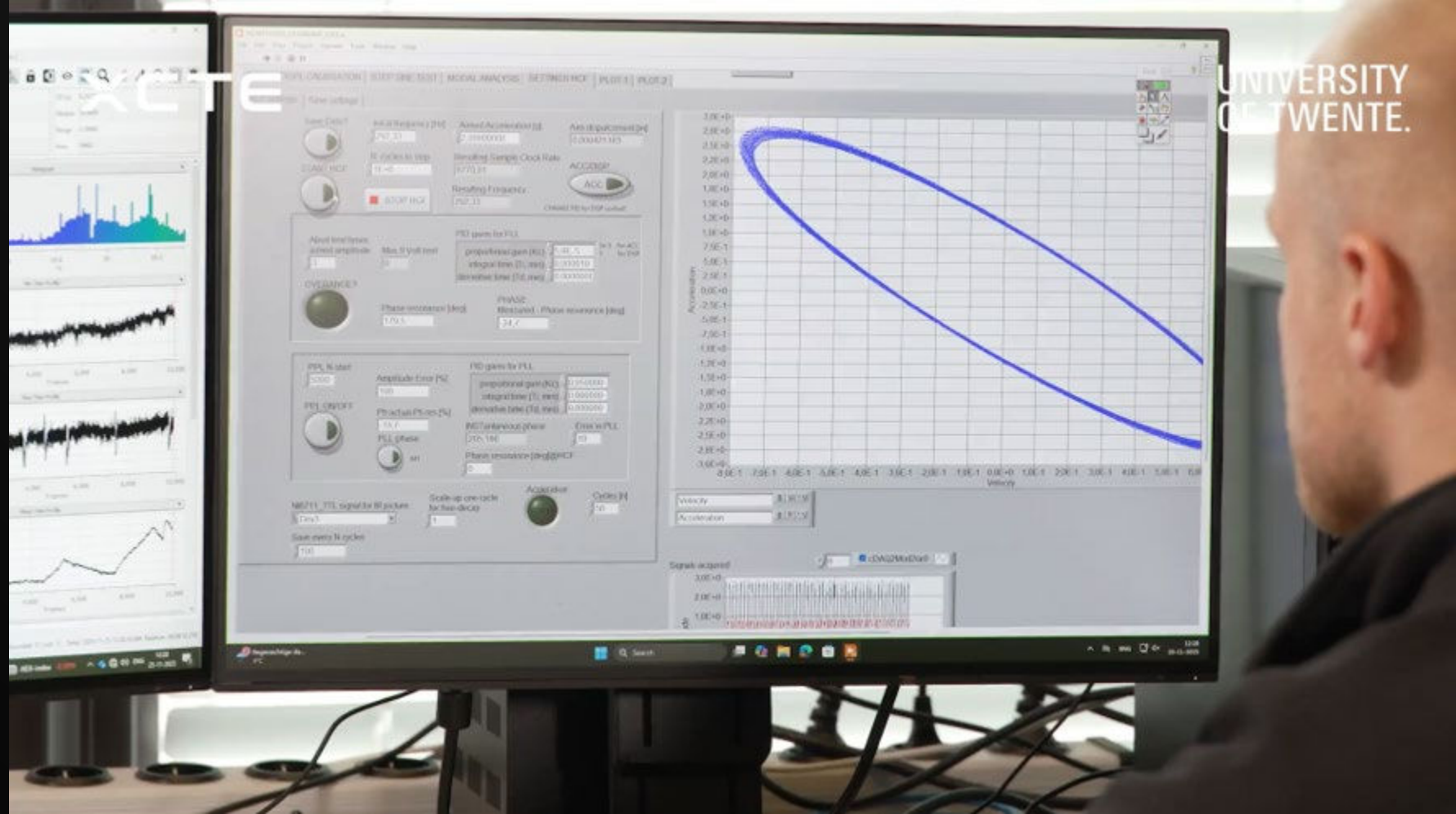


THE SETUP

1. LDV
2. Accelerometer
3. Shaker
4. Thermal Camera
5. (Environmental Chamber)



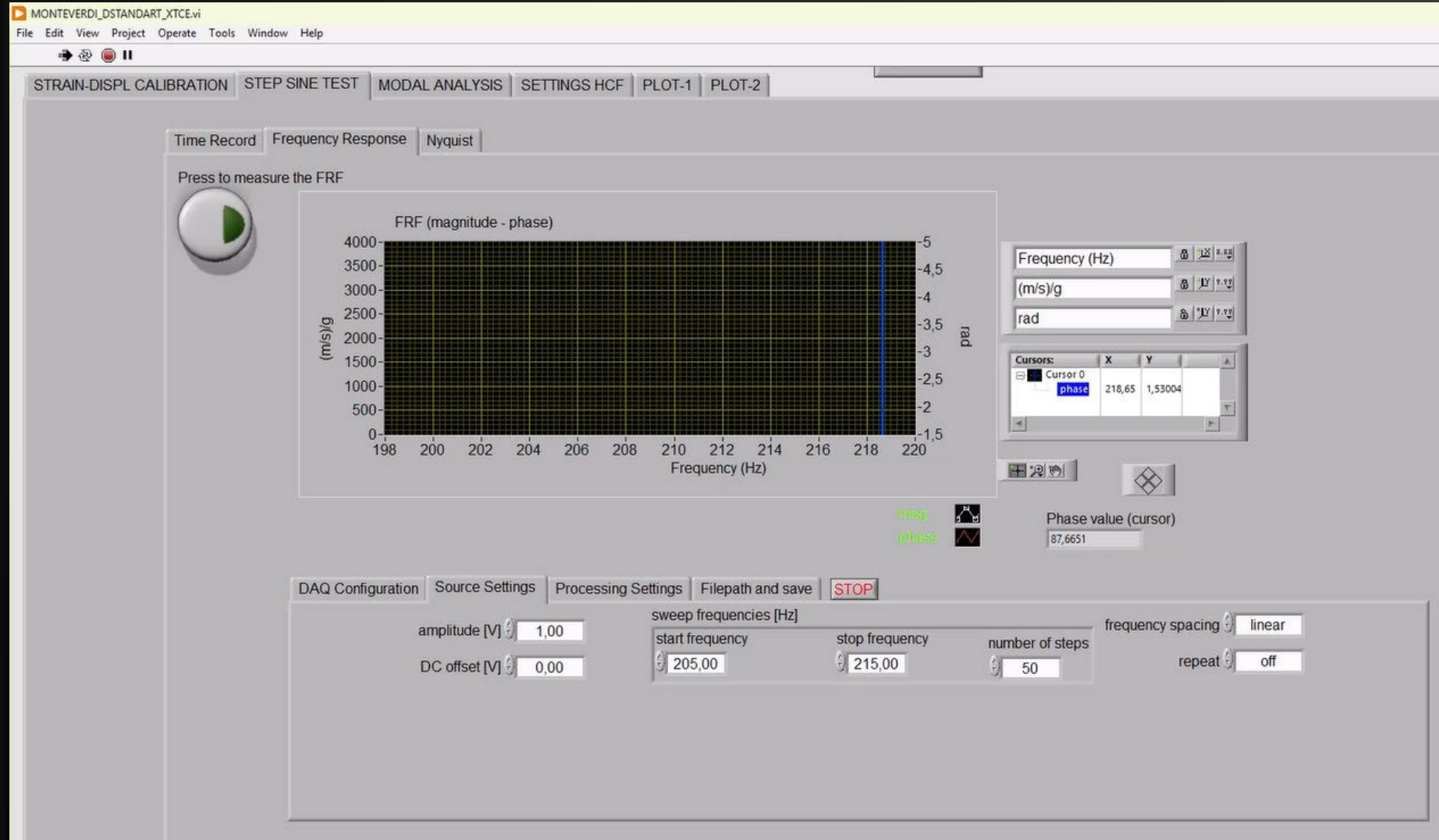
TESTING



UNIVERSITY OF TWENTE

FRF

- Find natural frequency



FRF

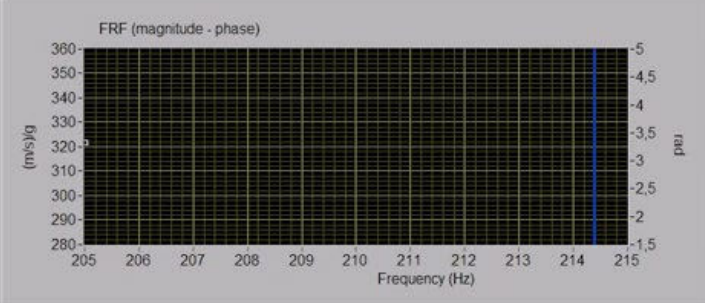
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File Edit View Project Operate Tools Window Help

STRAIN-DISPL CALIBRATION STEP SINE TEST MODAL ANALYSIS SETTINGS HCF PLOT-1 PLOT-2

Time Record Frequency Response Nyquist

Press to measure the FRF



FRF (magnitude - phase)

(m/s)/g

Frequency (Hz)

Phase value (cursor)

NaN

DAQ Configuration Source Settings Processing Settings Filepath and save STOP

amplitude [V] 1.00

DC offset [V] 0.00

sweep frequencies [Hz]

start frequency 205.00 stop frequency 215.00 number of steps 50

frequency spacing linear repeat off

Frequency (Hz) (m/s)/g rad

Cursors	X	Y
Cursor 0	214.39	NaN
phase		

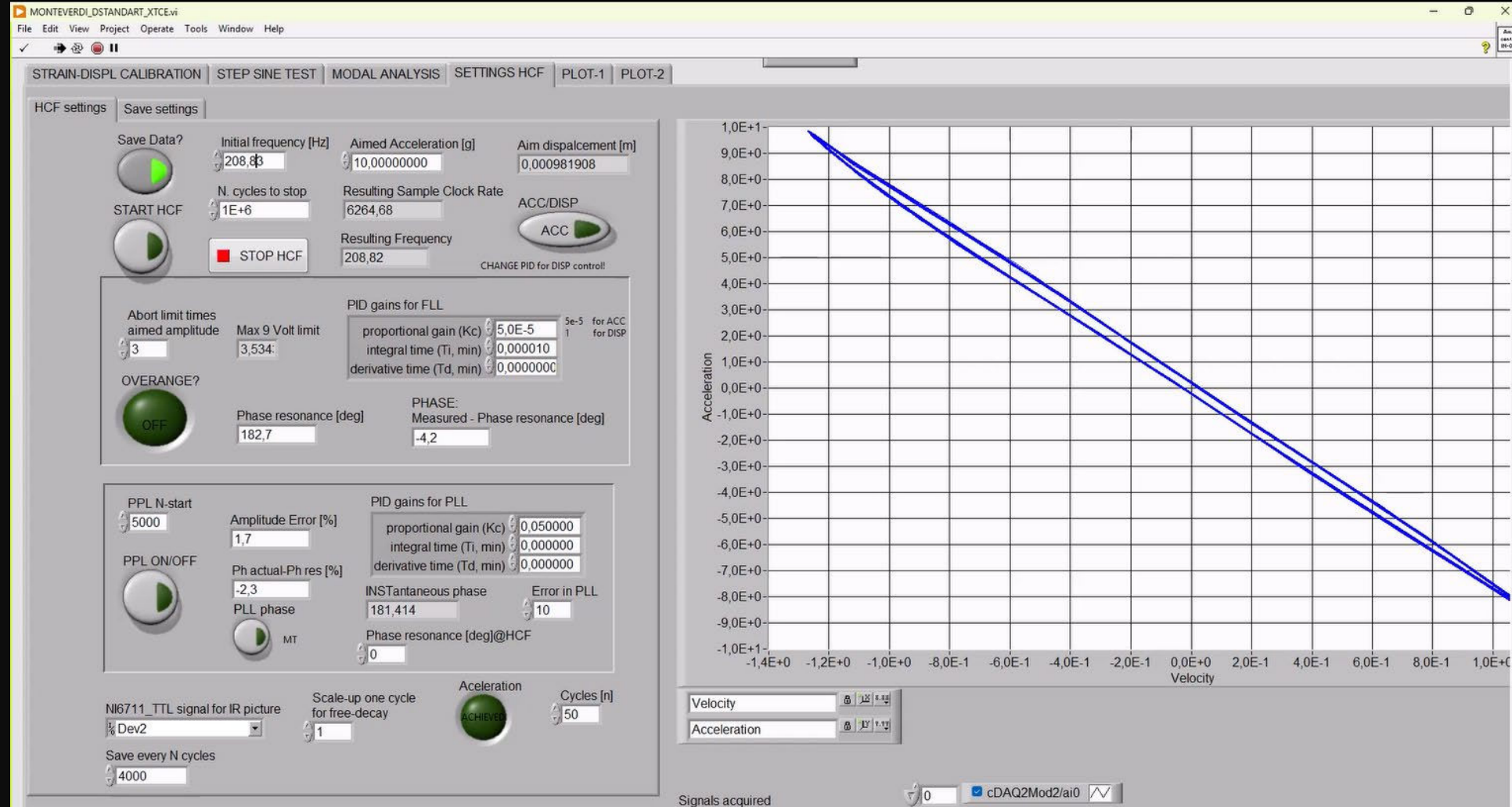
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Search

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HCF

- Control:
 - Acceleration
 - Displacement
 - Force
 - Phase



HCF

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STRAIN-DISPL CALIBRATION | STEP SINE TEST | MODAL ANALYSIS | SETTINGS HCF | PLOT-1 | PLOT-2

HCF settings | Save settings

Save Data? Initial frequency [Hz] 209,23 Aimed Acceleration [g] 10,00000000 Aim displacement [m] 7,93923E-5

START HCF N. cycles to stop 1E+6 Resulting Sample Clock Rate 3870,53 ACC/DISP ACC

STOP HCF Resulting Frequency 129,02 CHANGE PID for DISP control

Abort limit times aimed amplitude 3 Max 9 Volt limit 0,282

OVERANGE? OFF

Phase resonance [deg] 182,7 PHASE: Measured - Phase resonance [deg] 63,5

PID gains for FLL proportional gain (Kc) 5,0E-5 integral time (Ti, min) 0,000010 derivative time (Td, min) 0,0000000

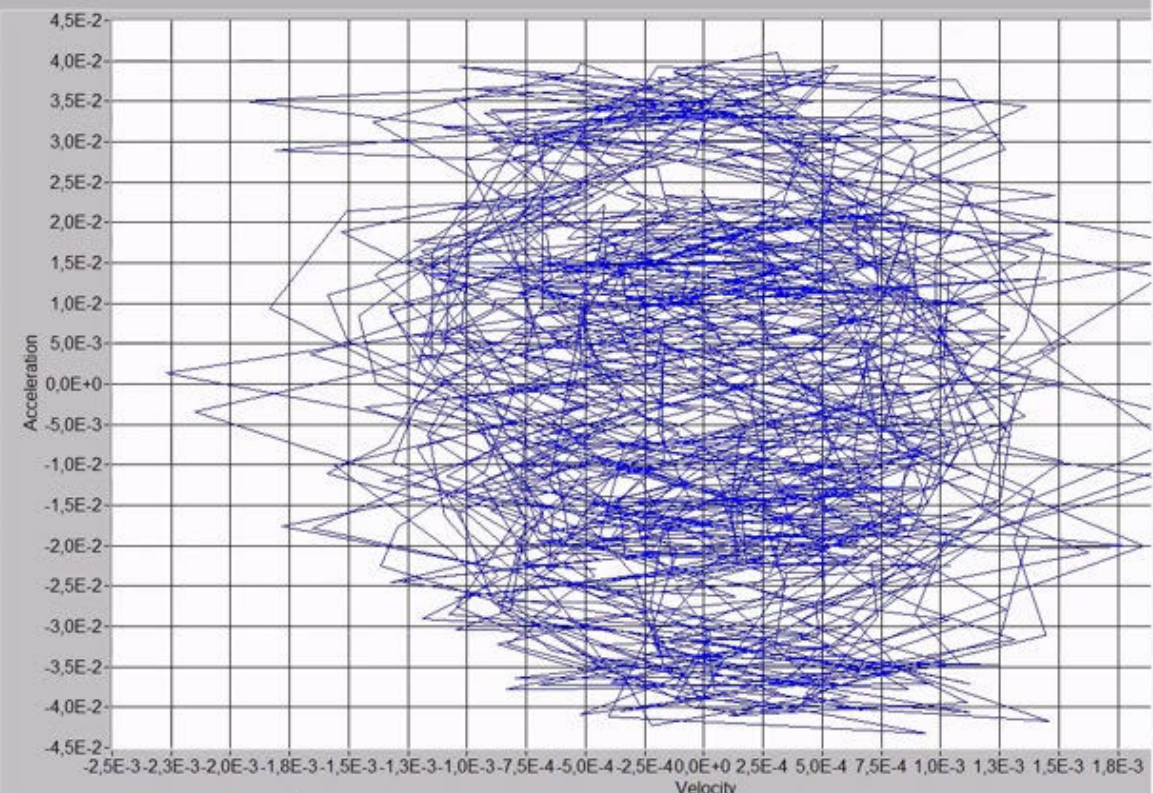
PPL N-start 5000 Amplitude Error [%] 5230,1

PPL ON/OFF Ph actual-Ph res [%] 31,6 INSTantaneous phase 95,5837 Error in PLL 10

PLL phase MT 0 Phase resonance [deg]@HCF 0

NI6711_TTL signal for IR picture % Dev2 Scale-up one cycle for free-decay 1 Acceleration Cycles [n] 50

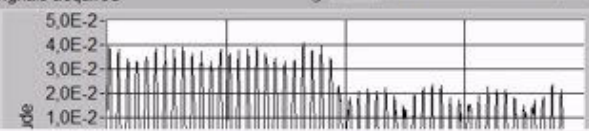
Save every N cycles 4000



Velocity Acceleration

Velocity 50 Acceleration 10

Signals acquired 0 cDAQ1Mod2/ai0



5.0E-2 4.0E-2 3.0E-2 2.0E-2 1.0E-2

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THERMAL CAM

- Nucleation location



Calibration

- Strain

NEW STRAIN CAL MODULE2.vi

File Edit View Project Operate Tools Window Help

DRIVE FREQUENCY (Hz) 202

Actual AMP 0,5

strain gage information

gage factor 2,1

nominal gage resistance 120

poisson ratio 0,3

bridge information

strain configuration Half Bridge I

lead wire resistance 4,2

initial bridge voltage 0

voltage excitation source Intern

voltage excitation value 2,5

minimum value Strain -0,0010000

maximum value Strain 0,0010000

stop STOP

LDV

ACC

Strain gauge

FINAL

MEASURED DATA

Time [s]	Strain	ACC	Strain
0,1	1,96417E-5	0,000146736	0,34026
0,2	1,96808E-5	0,000147105	0,34030
0,3	3,57111E-5	0,000273186	0,68443
0,4	3,57297E-5	0,000273542	0,68487
0,5	3,57375E-5	0,000273676	0,68514
0,6	3,57555E-5	0,000273896	0,68542
0,7	4,64059E-5	0,000363512	1,02391
0,8	4,63703E-5	0,000363472	1,02419
0,9	4,63768E-5	0,000363681	1,02462
1,0	4,63795E-5	0,000363916	1,02462
1,1	5,46507E-5	0,000436582	1,35473

Start Amp (V) 0,1

INC AMP (V) 0,1

Stop AMP (V) 0,5

N. of averages 4

Save Displ-Strain

Calibration

- Strain

NEW STRAIN CAL MODULE2.vi

File Edit View Project Operate Tools Window Help

stop STOP

DRIVE FREQUENCY (Hz) 202

Actual AMP 0,5

strain gage information

gage factor 2,1

nominal gage resistance 120

LDV

Time [s] m/s

STRAIN

ACC

Start Amp (V) 0,1

INC AMP (V) 0,1

Stop AMP (V) 0,5

N. of averages 4

MEASURED DATA

ACC	STRAIN	INC AMP (V)	Start Amp (V)
0,34026	1,96417E-5	0,000146736	0,1
0,34030	1,96808E-5	0,000147105	0,1
0,68443	3,57111E-5	0,000273186	0,2
0,68487	3,57297E-5	0,000273542	0,2
0,68514	3,57375E-5	0,000273676	0,2
0,68542	3,57555E-5	0,000273896	0,2
1,02391	4,64059E-5	0,000363512	0,3
1,02419	4,63703E-5	0,000363472	0,3
1,02462	4,63768E-5	0,000363681	0,3
1,02462	4,63795E-5	0,000363916	0,3
1,35473	5,46507E-5	0,000436582	0,4

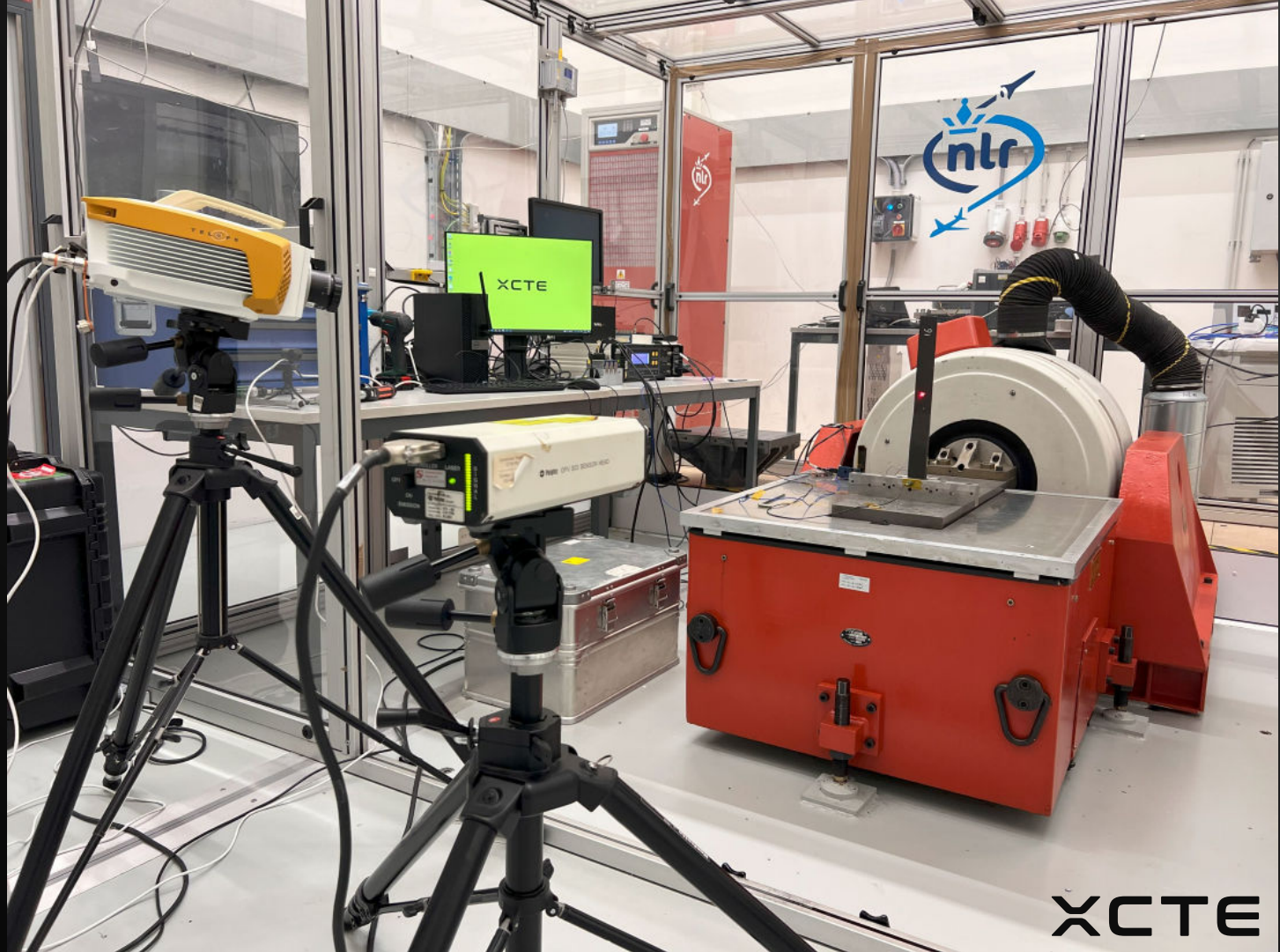
spl-Strain

OTHER LABS

NLR (2025) >

Aerospace Demo >

Strain calibration >



XCTE

OTHER LABS

NLR (2025) >

Aerospace Demo >

Strain calibration >



XCTE

OTHER LABS

NLR (2025) >

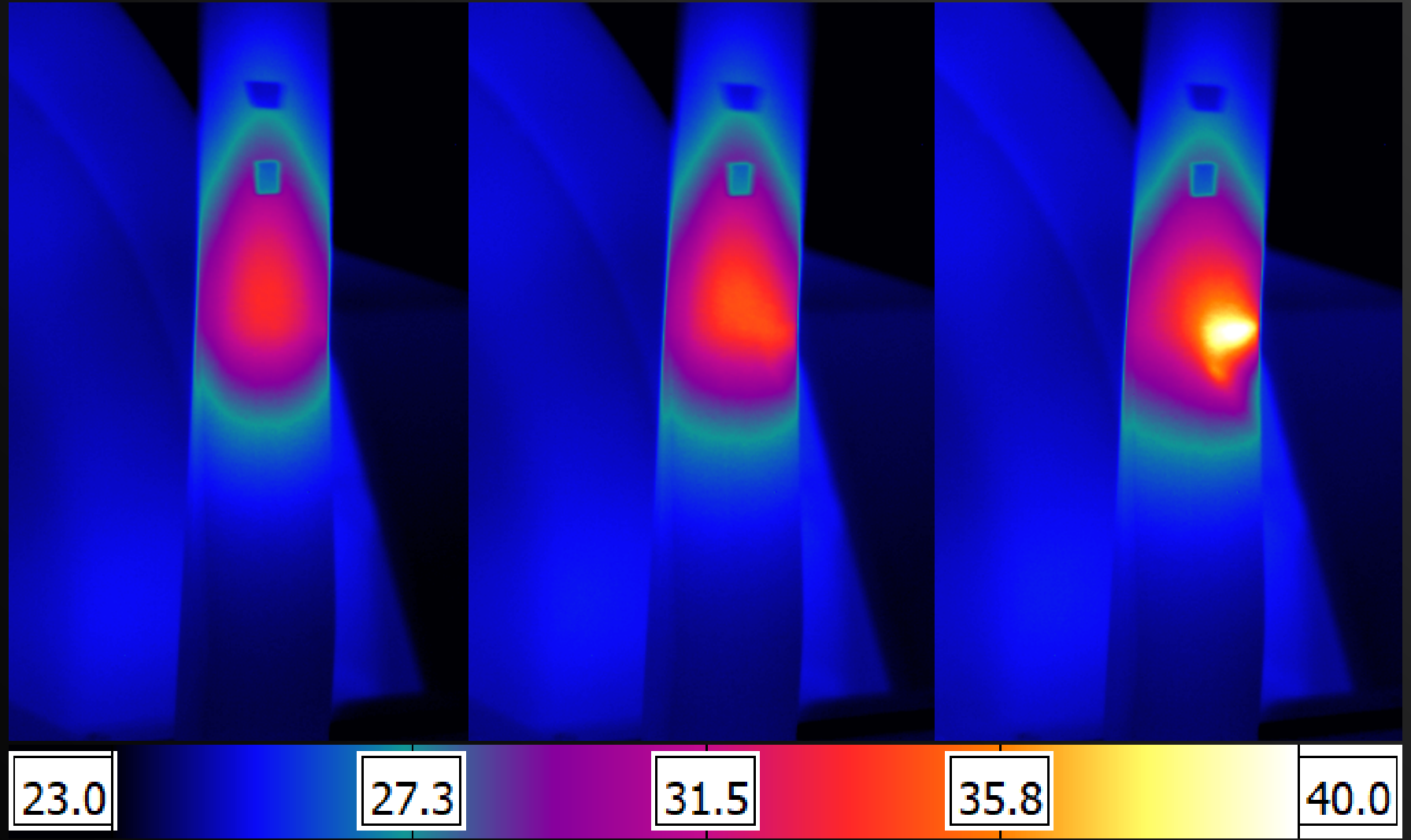
Aerospace Demo >

Strain calibration >



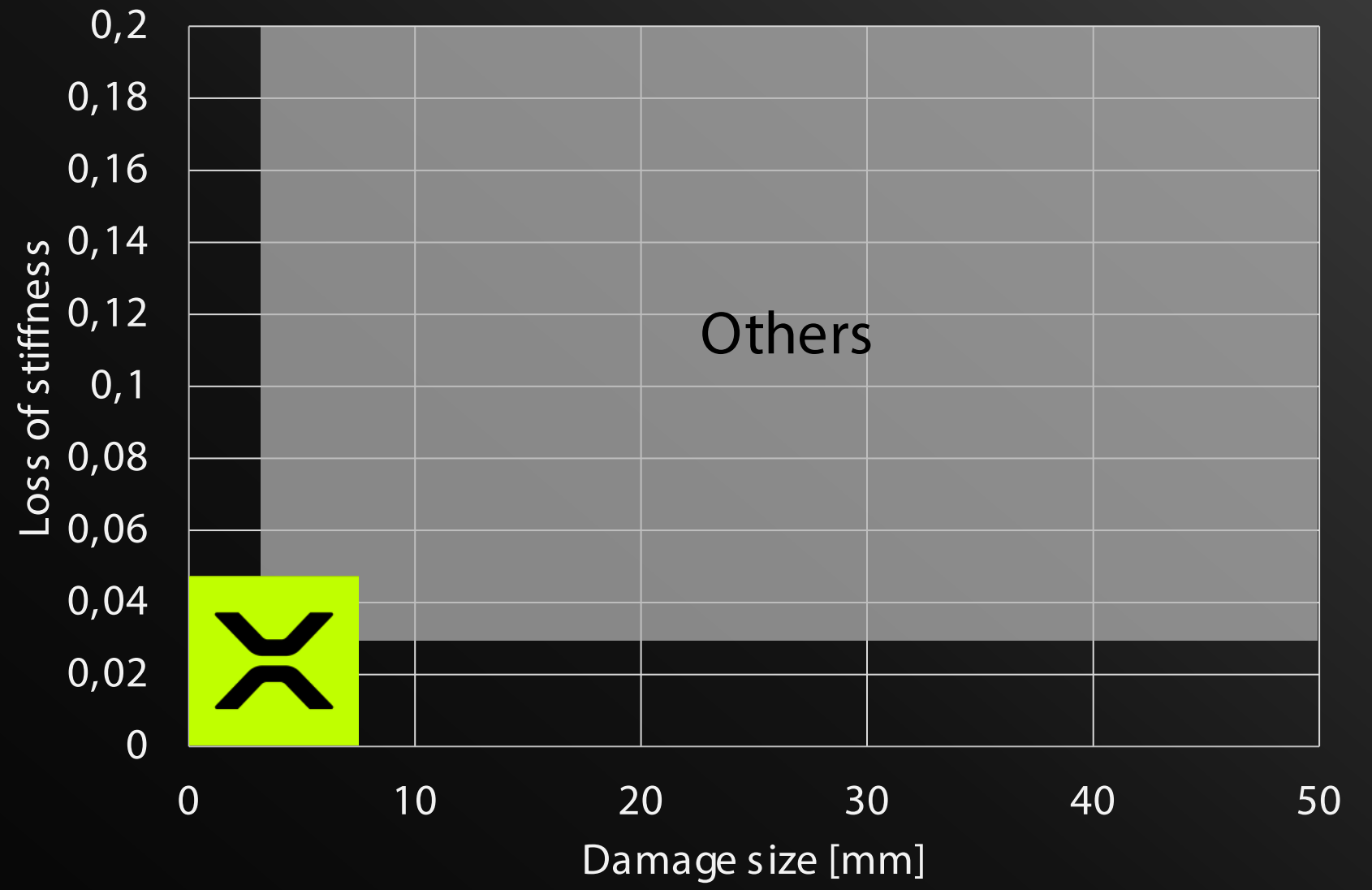
OTHER LABS

Thermal images



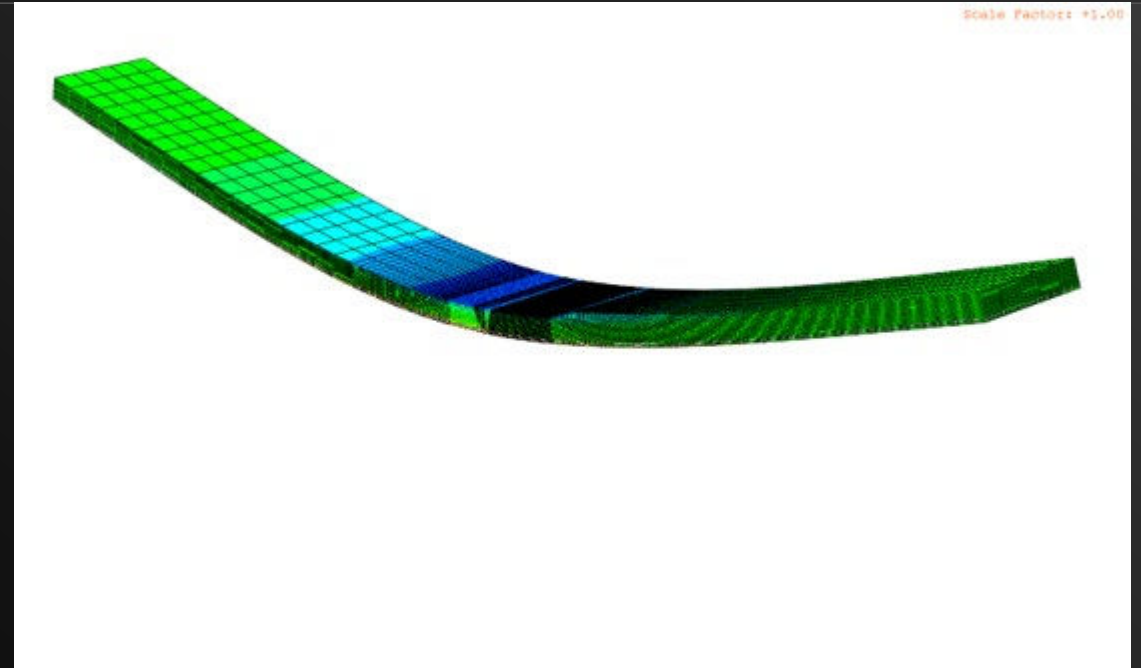
DATA ANALYSIS & EXPLOITATION

OUR BUSINESS OPERATION



PHASE TRACKING

- The rotational stiffness depends on the second moment of area and the length.
- The ATAN function transforms an extremely small change (I and L) into a large phase shift (ϕ).
- Any damage onset is detected.



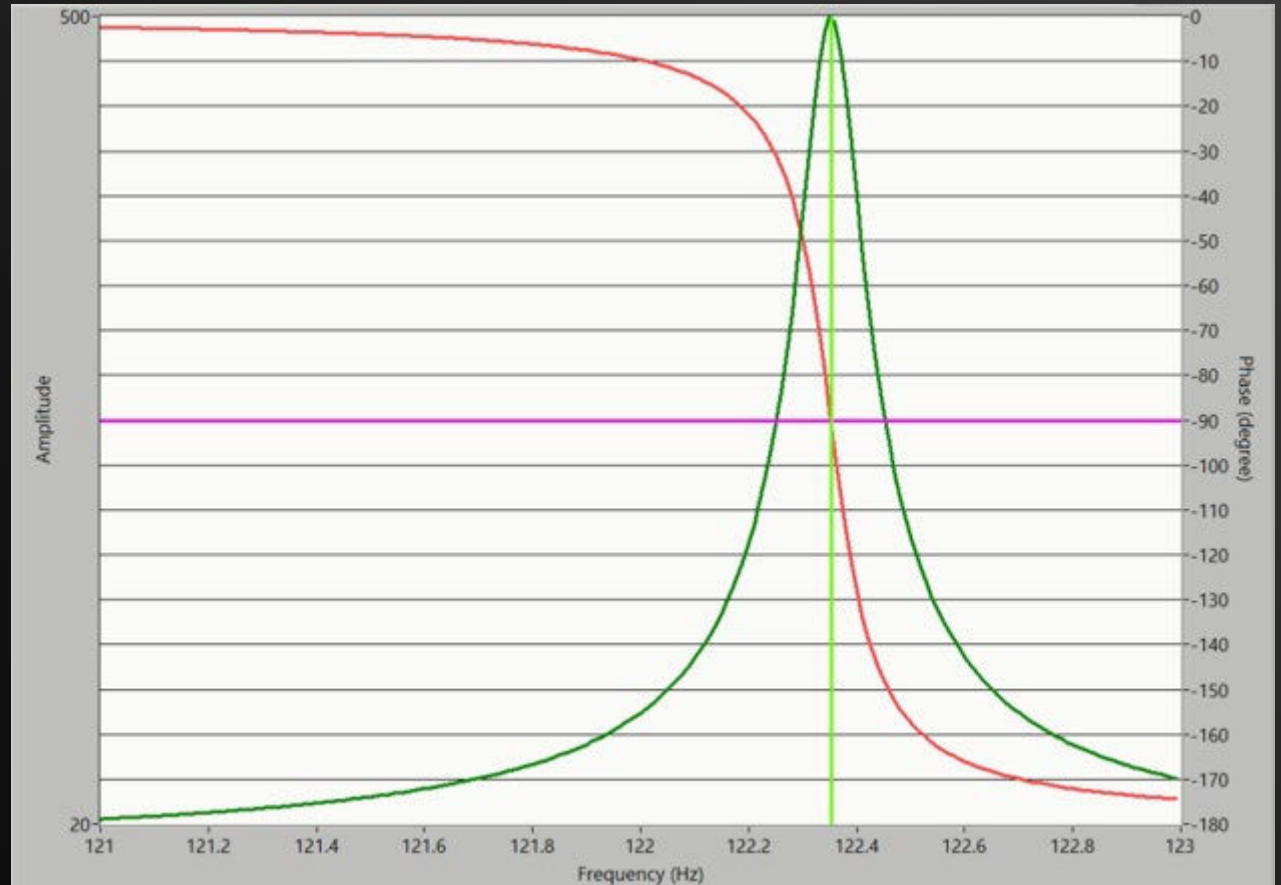
$$k_{\theta} = \frac{2EI_1I_2I_3}{(L - L_2)I_2I_3 + 2L_2I_1I_3 + (L - L_2)I_1I_2}$$

$$\omega_n^2 = \frac{k_{\theta}}{m_{eff}}$$

$$\phi(\bar{\omega}) = \arctan\left(-\frac{\eta\omega_n^2}{\omega_n^2 - \bar{\omega}^2}\right) \quad \bar{\omega} = \text{const}$$

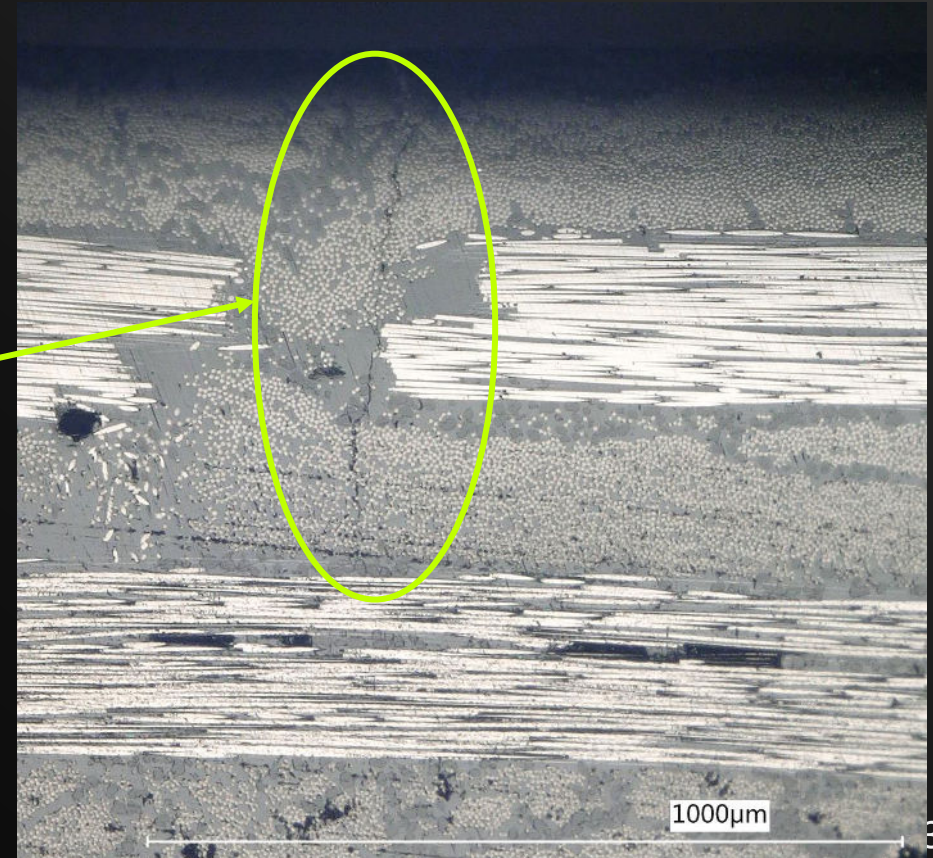
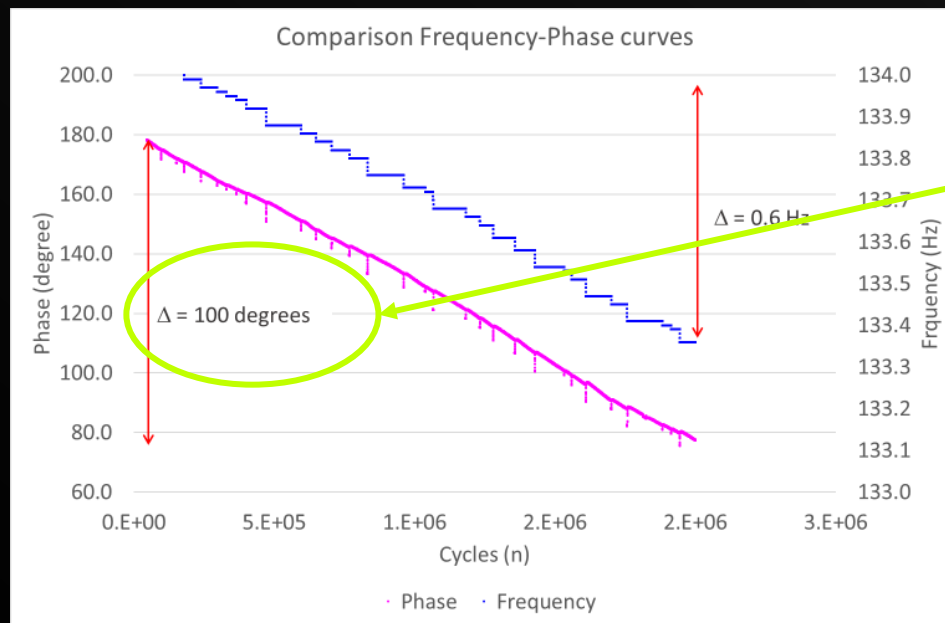
PHASE TRACKING

- The green line is the fixed excitation frequency $\bar{\omega} = \text{const.}$
- The system dynamics changes because of the fatigue damage.
- The phase curve is very steep around the resonance, and so sensitive.



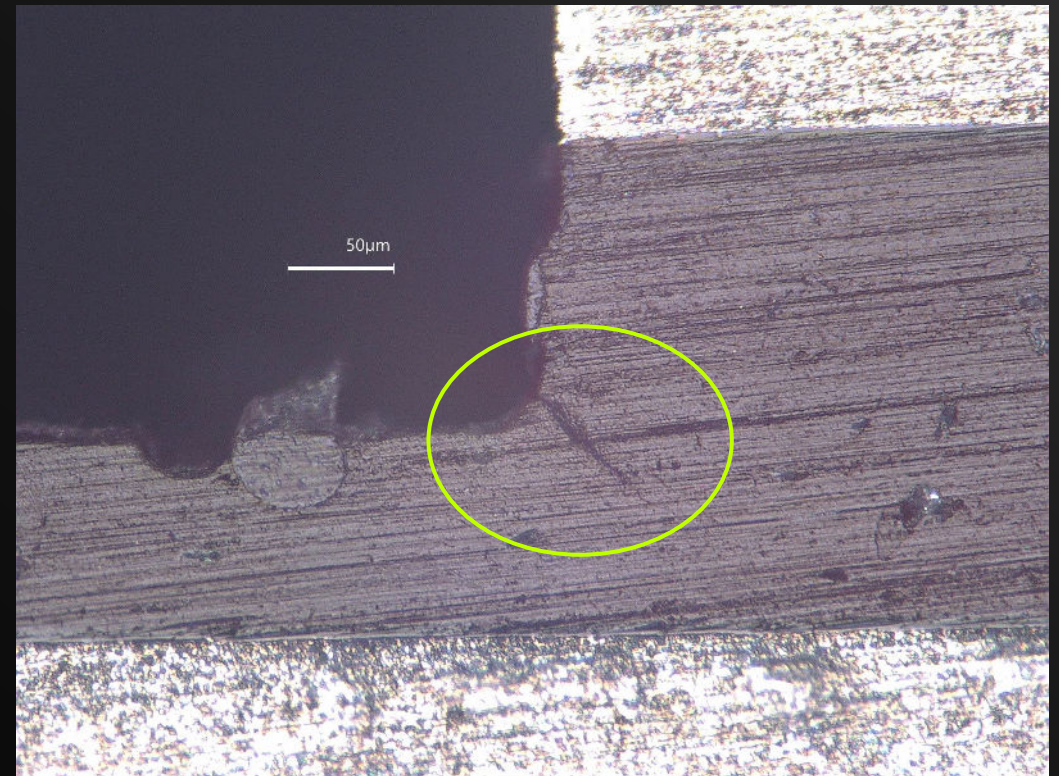
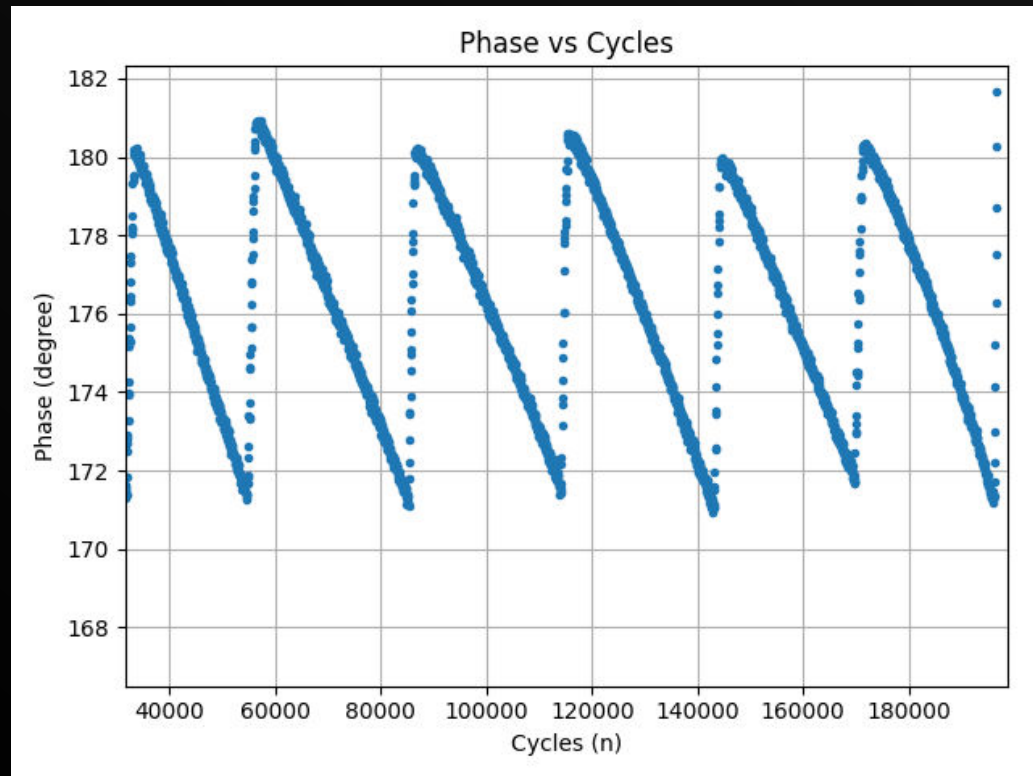
SENSITIVITY TO FATIGUE DAMAGE ONSET

- An example of phase data shows the damage accumulation over the number of cycles.
- Experimental case (M21T700 sample)



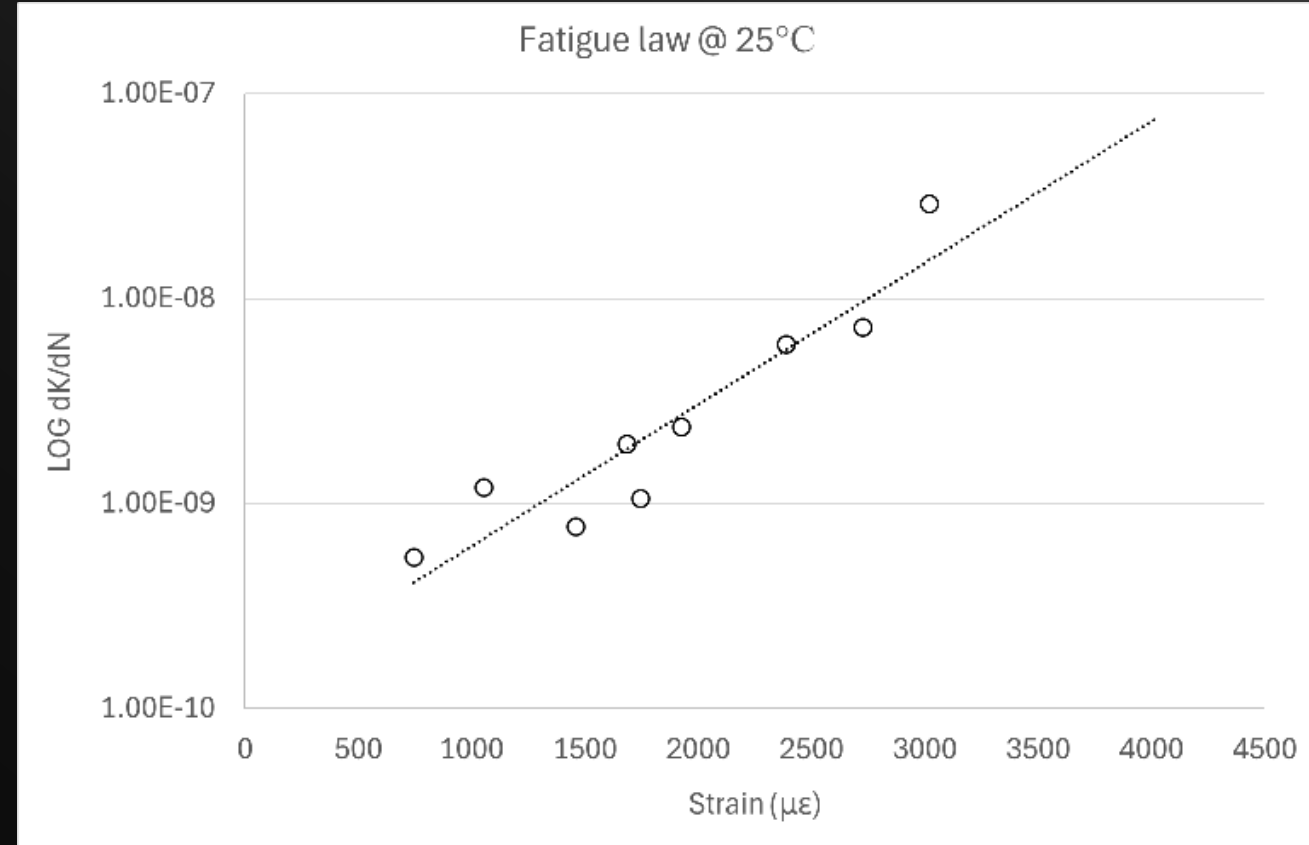
SENSITIVITY TO FATIGUE DAMAGE ONSET

- Lap-joint with adhesive shows a small damage 50 microns after several frequency adjustments for phase tracking.



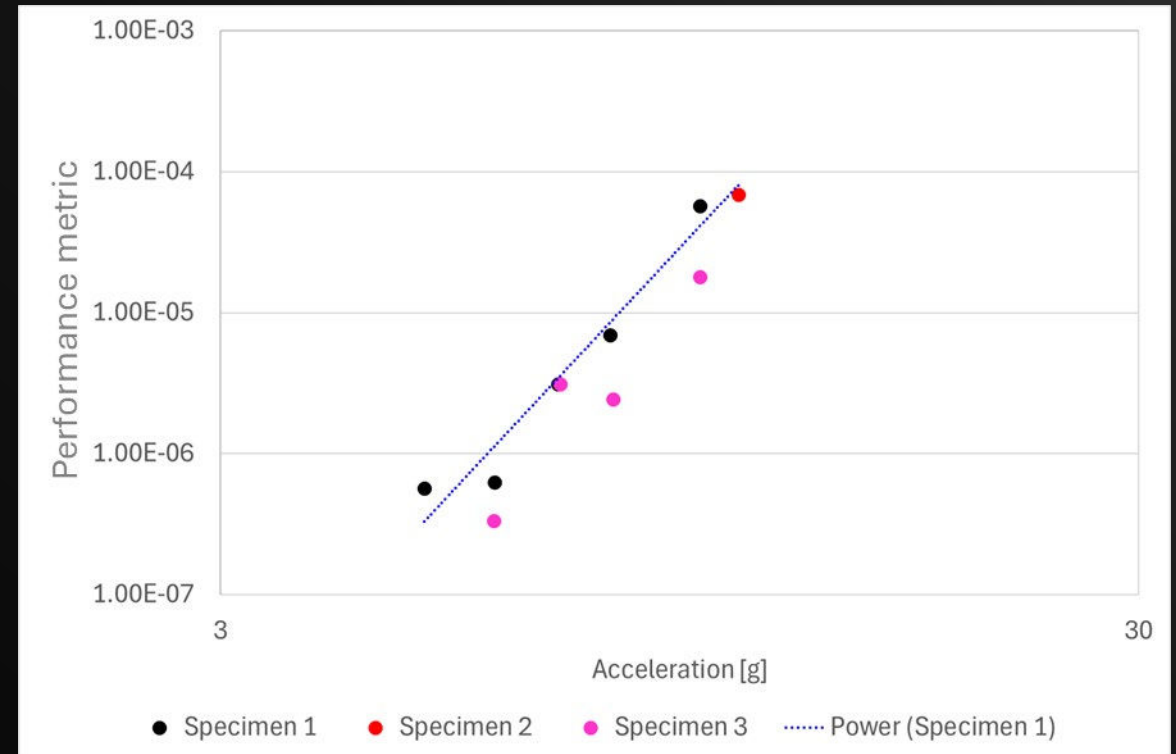
FATIGUE LAW

- The raw data are processed to produce a relationship between the input load and the output loss of stiffness.
- Note that the loss of stiffness is small because of onsets.



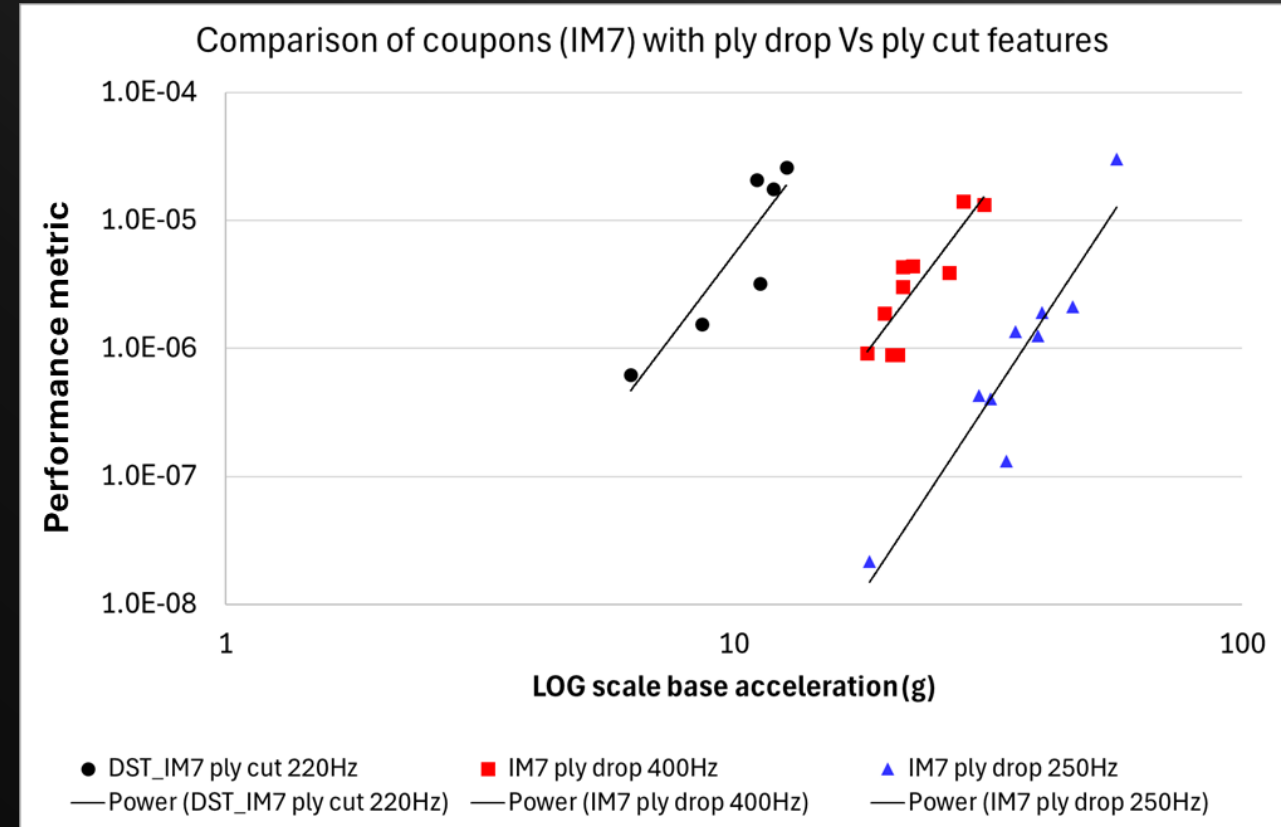
FULL SCALE TESTING

- An incremental step test can be sufficient to define the fatigue law.
- The specimen-2 (red) follows the same power law of specimen-1.



FATIGUE BEHAVIOUR OF STRUCTURES

- Fatigue of different structures can be compared.
- Based on the performance metric, being that measure by stiffness loss or else.



THE APPLICATIONS

The Impact



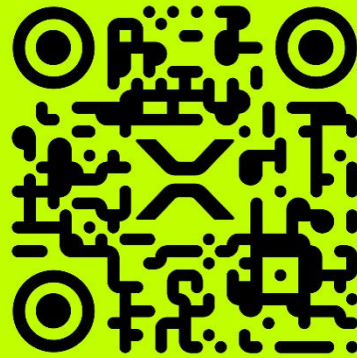
Fast design comparison



Unlock full material potential



Reduced time to market



XCTE.eu

Testing at the speed of innovation

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Linkedin: www.linkedin.com/company/xcte/